<u>Solution QI</u> Let $\delta > 0$ and $b_1, \dots, b_n > 0$ be such that $I \times J \subseteq U$ where $I = [x_0 - \delta, x_0 + d]$ and $J = \prod_{i=1}^n [y_i^2 - b_i, y_i^2 + b_i]$. Since h is continuous and $I \times J$ is compact, $\|h(x, \underline{u})\| \leq M$ for some fixed M and all $(\varkappa, \underline{u}) \in I \times J$. We may assume $\chi \delta < 1$ and $M \delta < b_i$ for all $|\leq i \leq N$. Define

$$f: C + (I, J) \longrightarrow C + (I, J)$$

$$f(\underline{\mathcal{I}})(x) = \left(y_i^{\circ} + \int_{x_o}^{\infty} h_i(t, \underline{\mathcal{I}}(t)) dt \right)_{i=1}^{\circ}$$

We put the d_1 -metric (i.e. $\|-\|$) on $J \subseteq \mathbb{R}^n$, and aim to prove that with respect to the inclured d_{∞} -metric on $Cts(\mathcal{I}, \mathcal{J})$, f is a contraction mapping. Note that to check f is well-clefined it suffices as before to check that $f(\underline{f})(\underline{I}) \subseteq \overline{J}$ for all $\underline{f} \in Cts(\mathcal{I}, \mathcal{J})$ which follows from

$$\left|\int_{x_{o}}^{x}h_{i}\left(t,\underline{\mathcal{I}}(t)\right)dt\right| \leq \int_{x_{o}}^{x}\left|h_{i}\left(t,\underline{\mathcal{I}}(t)\right)\right|dt \leq MS < b_{i}.$$

To check f is a contraction, we compute

$$d_{\infty}(f \underline{\mathcal{Y}}, f \underline{\mathcal{Y}}) = \sup \{ \| f(\underline{\mathcal{Y}})(x) - f(\underline{\mathcal{Y}})(x) \| | x \in I \}$$

$$= \sup \{ \sum_{i=1}^{n} | \int_{x_{0}}^{x} h_{i}(t, \underline{\mathcal{Y}}(t)) dt - \int_{x_{0}}^{x} h_{i}(t, \underline{\mathcal{Y}}(t)) dt | x \in I \}$$

$$\leq \sup \{ \sum_{i=1}^{n} \int_{x_{0}}^{x} | h_{i}(t, \underline{\mathcal{Y}}(t)) - h_{i}(t, \underline{\mathcal{Y}}(t)) | dt | x \in I \}$$

$$= \sup \{ \int_{x_{0}}^{x} \| h(t, \underline{\mathcal{Y}}(t)) - h(t, \underline{\mathcal{Y}}(t)) \| dt | x \in I \}$$

$$\leq \sup \{ \int_{x_{0}}^{x} \alpha \| \underline{\mathcal{Y}}(t) - \underline{\mathcal{Y}}(t) \| dt | x \in I \}$$

$$\leq \sup \{ \int_{x_{0}}^{x} \alpha d_{\infty}(\underline{\mathcal{Y}}, \underline{\mathcal{Y}}) dt | x \in I \} \leq \alpha \delta d_{\infty}(\underline{\mathcal{Y}}, \underline{\mathcal{Y}}) \cdot \Box$$

<u>Solution Q2</u> Let S_* , S_{**} be the respective sets of solutions. Define $\Lambda : S_* \longrightarrow S_{**}$ by $\Lambda(\mathfrak{f}) = (\mathfrak{f}, \mathfrak{f}', ..., \mathfrak{f}^{(n-1)})$

This is well-defined since if $J \in S_*$ it is n-times differentiable, so all derivatives up to $\mathcal{J}^{(n-1)}$ are differentiable hence continuous, and it is clear $\Lambda(\mathcal{I}) \in S_{**}$. Define $\Theta: S_{**} \longrightarrow S_*$ by $\Theta(\mathcal{T}_0, \dots, \mathcal{Y}_{n-1}) = \mathcal{Y}_0$. This is n-times continuously differentiable with $\mathcal{Y}_i = \mathcal{Y}_i', \dots, \mathcal{Y}_{n-1} = \mathcal{Y}_0^{(n-1)}$ and

$$\Upsilon_{o}^{(n)}(x) = h\left(x, \Psi_{o}(x), \Upsilon_{o}^{\prime}(x), \ldots, \Upsilon_{o}^{(n-1)}(x)\right)$$

so that $Y_0 \in S_*$. Since clearly $\Lambda \ominus = id$, $\Theta \Lambda = id$ this completes the pworf. \Box

<u>Solution Q3</u> It is equivalent to solve the system (wordinates α , uo, u₁ on \mathbb{R}^3)

$$\begin{aligned} \psi_{o}^{\prime} &= \psi_{1} & \qquad \psi_{o}(o) = 0 & \qquad h_{o} = u_{1} \\ \psi_{1}^{\prime} &= -\psi_{o} & \qquad \psi_{1}(o) = 1 & \qquad h_{1} = -u_{o} \\ x_{o} = 0 & \qquad \\ x_{o} = 0 & \qquad \\ y_{0}^{\circ} &= (o, 1) \\ \end{aligned}$$

$$\begin{aligned} f: \ C_{t_{n}}(\mathbb{I}, \mathbb{J}) &\longrightarrow C_{t_{n}}(\mathbb{I}, \mathbb{J}) \\ f(\underline{\Psi})(\mathbf{x}) &= \Big(\int_{0}^{\mathbf{x}} h_{0}(t, \mathcal{K}(t), \Psi_{1}(t)) dt, \ 1 + \int_{0}^{\mathbf{x}} h_{1}(t, \mathcal{K}(t), \Psi_{1}(t)) dt \Big) \\ &= \Big(\int_{0}^{\mathbf{x}} \Psi_{1}(t) dt, \ 1 - \int_{0}^{\mathbf{x}} \Psi_{0}(t) dt \Big) \end{aligned}$$

starting with some initial $\Psi \equiv (0, 1)$. Note h is defined on all of $U = IR^3$, and if we choose $b_p = b_i = b$ then $\|\underline{h}(x, u, v)\| = |u| + |v| \leq b + 1 + b = 2b + 1$. Note that

$$\| h(x,u,v) - h(x,u',v') \| = \| (v,-u) - (v',-u') \|$$
$$= \| (v-v',u'-u) \|$$
$$= \| v-v' \| + \| u-u' \|$$
$$= \| (u,v) - (u',v') \|$$

so any $\alpha \ge 1$ will do. We want to take S as large as possible with $\alpha \le 1$ so we take $\alpha = 1$. We take M = 2b+1 so that

$$b/M = b/2b+1$$
.

Taking b arbitrarily large ^b/M is as close to $\frac{1}{2}$ as we wish, and we can arrange $M\delta < b$ by taking δ to be any fixed value $\delta < \frac{1}{2}$. This fixes all the hypotheses, and on $I = [-\delta, \delta]$ we compute that the following sequence converges uniformly to a unique so lution:

$$\begin{split} \underline{\gamma}^{\circ} &= (0, 1) \\ \underline{\gamma}^{I} &= f(\underline{\gamma}^{\circ}) = (x, 1) \\ \underline{\gamma}^{2} &= f(\underline{\gamma}^{\circ}) = (x, 1 - \frac{1}{2}x^{2}) \\ \underline{\gamma}^{3} &= f(\underline{\gamma}^{\circ}) = (x - \frac{1}{2} \cdot \frac{1}{3}x^{3}, 1 - \frac{1}{2}x^{2}) \\ \underline{\gamma}^{4} &= f(\underline{\gamma}^{3}) = (x - \frac{1}{2} \cdot \frac{1}{3}x^{3}, 1 - \frac{1}{2}x^{2} + \frac{1}{4!}x^{4}) \end{split}$$

and so clearly the limit is $\underline{Y}^* = (sin(x), cos(x))$, yielding the solution sin(x) to the original IVP.

6)