[Q] What does the Gram-schmidt process do? (Do not give the algorithm, just describe at a high level what the input and output of the algorithm are).

 \square Any real symmetric matrix A is diagonalisable (you may assume this). Show that there is an <u>orthogonal</u> matrix Q with $Q^T A Q$ diagonal.

<u>Definition</u> If V is a vector space, a function $B: V \times V \longrightarrow IR$ is <u>bilinear</u> if

(i) B(x+x',y) = B(x,y) + B(x',y) $\forall x, x', y \in V$ (ii) B(x,y+y') = B(x,y) + B(x,y') $\forall x,y,y' \in V$ (iii) $B(\lambda x,y) = B(x, \lambda y) = \lambda B(x,y)$ $\forall x,y \in V$ $\forall \lambda \in \mathbb{R}$.

We say B is symmetric if B(x,y) = B(y,x) for all $x,y \in V$.

[Q3] Rove that there is a bijection between bilinear forms on V and linear maps $V \longrightarrow V^*$ where V^* denotes the dual space, where the linear map for associated to B is $f_B(x)(y) = B(x,y)$.

Q5] Prove that if B is a symmetric bilinear form on \mathbb{R}^n there is a unique symmetric PEMn(R) with $B(\underline{\vee},\underline{\vee}) = \underline{\vee}^T P \underline{\vee}$ for all $\underline{\vee},\underline{\vee} \in \mathbb{R}^n$. We denote this bilinear form $(\underline{\vee},\underline{\vee}) \mapsto \underline{\vee}^T P \underline{\vee}$ by BP. What condition does nondegeneral of Bp place on P? (

A quadratic space is a pair (V, B) where V is a finite-dimensional vector space and B is a symmetric bilinear form on V. Two quadratic spaces (V,B), (V,B')are equivalent and we write $(V,B) \sim (V',B')$ if there is a linear isomorphism. $F: V \rightarrow V'$ with B'(Fx,Fy) = B(x,y) for all $x,y \in V$.

 \square Given symmetric matrices $P, P' \in Mn(\mathbb{R})$ write the condition

$(\mathbb{R}^n, \mathbb{B}_P) \sim (\mathbb{R}^n, \mathbb{B}_{P'})$

purely in terms of matrices.

 $\overline{[Q7]}$ (sylvester's law of inertia) Prove that any quadratic space (V, B) with B nondegenerate is equivalent, for a unique pair of integers $a_1b > 0$ with a+b=n, to the pair (\mathbb{R}^n , $\mathbb{B}^{a,b}$) where \mathbb{B}^{a_1b} is the bilinear form associated to the matrix

$$\operatorname{diag}\left(\underbrace{+1,+1,\ldots,+1,-1,\cdots,-1}_{a}\right).$$

The pair (9,b) is called the <u>signature</u> of B, and the group O(9,b) is the associated isotropy group

$$O(q,b) := \{ F: V \rightarrow V \mid F \text{ is a linear iso., and} \\ B(Fx, Fy) = B(x,y) \forall x, y \in V \}.$$

<u>Remark</u> Minkowski space has signature (3,1), hence the <u>Lorentz group</u> is denoted O(3,1) (or in lectures O(2,1) since we had two space directions).

2

dimV=n